

# HEIDENHAIN



Product Information

### **ERO 2000 Series**

Angle Encoders Without Integral Bearing

### **ERO 2000 series**

- High resolution and accuracy
- Low mass and low mass moment of inertia
- Consisting of an AK scanning head and TKN circular scale
- TKN segment versions with position detection via homing track



A 0.005 A

0.003

(Ø 5.2)

(Ø 13.2)

#### Graduation carrier Ø 18.6 mm (segment version: 18.6 mm x 9 mm)

0.75±0.01

3h6

(R)

Ø 18.6

AK ERO 20x0	<b>TKN ERO 2000</b>		
	2.1		

Æ

0 O





B D LE

(12.7)

3x M2

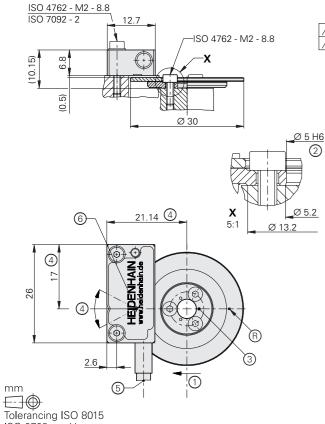
⊕ Ø 0.1 ►

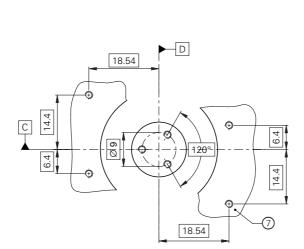
0.05/12.7 B C LE

2x M2 (

⊕ Ø 0.1

// 0.1/26





A

В

ISO 2768 - m H < 6 mm: ±0.2 mm

 $\square$  = Bearing

- Reference mark
- 1 = Positive direction of rotation
- 2 = Centering collar
- 3 = Marks for circular scale centering (3x120°)
- 4 = Fine adjustment of the scanning head for obtaining optimal incremental signals
- 5 = Alternative cable outlet and connector are available
- 6 = Optical center point
- 7 = For centering of circular scale with two scanning heads

LE = Line element (ISO 1101: 2008)

- €71) X 8. Ø 3.7 5 2:1 2:1 22.5 22.50 -0 HOMING LOW level HIGH level °±5° 6 93.3°  $\mathbb{C}$ www.heidenhain.de
- $\mathbb{B}$  = Bearing of mating shaft
- R = Position of the reference mark

Product Information ERO 2000

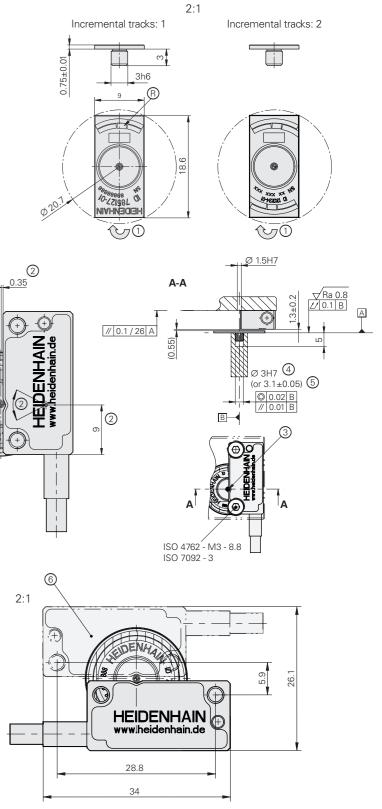
- 1 = Direction of shaft rotation for ascending position values
- 2 = Fine adjustment of the scanning head for optimal incremental signals
  3 = Cylindrical pin for positioning and Moiré adjustment (must be removed after positioning)
- 4 = Dimension for alignment of the circular scale via the centering pin of the graduated disk
- 5 = Dimension for mounting the graduated disk via optical alignment;

01/2022

- do not use the outer glass edge of the graduated disk
- 6 = Optional: mounting with two scanning heads



**TKN ERO 2002** 



mm Tolerancing ISO 8015 ISO 2768 - m H < 6 mm: ±0.2 mm

### Specifications

Scanning head	AK ERO 2080		
Interface	$\sim$ 1 V <sub>PP</sub>		
Reference mark signal	Square-wave pulse		
Cutoff frequency –3 dB <sup>1)</sup>	≥ 1 MHz		
Electrical connection*	15-pin D-sub connector (male) with 0.5 m/1 m/1.5 m/3 m cable 12-pin SHR-12V-S connector (female) with 0.5 m/1 m/1.5 m/3 m cable Cable outlet on the left or right and straight or angled		
Cable length	With HEIDENHAIN cable: $\leq$ 20 m; during signal adjustment with the PWM 21: $\leq$ 3 m		
Supply voltage	DC 5V ±0.5V		
Current consumption	≤ 150 mA (without load)		
Vibration 55 Hz to 2000 H Shock 6 ms	$z \leq 500 \text{ m/s}^2 \text{ (EN 60068-2-6)} \\\leq 1000 \text{ m/s}^2 \text{ (EN 60068-2-27)}$		
Operating temperature	-10 °C to 70 °C		
Protection	IP50		
Mass Scanning he Connector Cable	$\approx 5 g \text{ (without cable)} \leq 75 g \approx 22 g/m$		

\* Please select when ordering <sup>1)</sup> Maximum frequency during referencing: 500 kHz

Circular scale	TKN ERO 2000 (full circle)		
Measuring standard	SUPRADUR graduation on gla		
Measuring range	360°		
Signal periods	4096	2500	
Accuracy of graduation <sup>2)</sup>	±8"	±10"	
Position error per signal period <sup>37</sup>	±0.3"	±0.5	
Position noise RMS (1 MHz)	0.03"	0.04′	
Reference marks	One		
Inside diameter of hub	5 mm	-	
Dimensions of graduation carrier	Ø 30 mm	Ø 18	
Centering pin	-	3 mn	
Mech. permissible shaft speed	≤ 14000 rpm	≤ 24	
Moment of inertia	$4.1 \cdot 10^{-7}  \text{kgm}^2$	2.2 ·	
Protection EN 60529	Complete, mounted encoder:		
Mass	≈ 5.2 g	≈ 0.5	

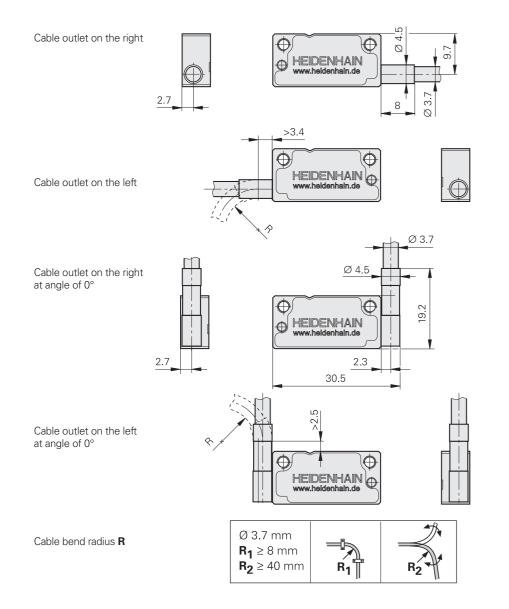
1) Along with their incremental graduation, the TKN ERO 2002 segment versions feature a homing track for position detection (see 🕀 in Along with their incremental graduation, the TKN ENO 2002 segment versions leading a homing track for position detection (see (e) in mating dimensions). The signal for position detection from the scanning head is transmitted in the TTL level via a separate line and is therefore directly available. The incremental signals correspond to the V<sub>PP</sub> interface.
 <sup>2)</sup> When centered with two scanning heads
 <sup>3)</sup> The position error within one signal period and the accuracy of the graduation together yield the encoder-specific error; for additional mounting and bearing errors of the measured shaft, see *Measuring accuracy* in the *Modular Angle Encoders With Optical Scanning*

brochure.

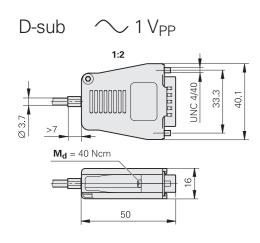
	TKN ERO 2002 <sup>1)</sup> (segm	ent)		
SS				
	45°			
)	2500 over 360°			
,	-	-		
"	±0.5"			
11	0.04"			
	One	One on every side		
	-			
.6 mm	18.6 mm x 9 mm			
n	3 mm			
000 rpm				
10 <sup>-8</sup> kgm <sup>2</sup>	1.1 · 10 <sup>-8</sup> kgm <sup>2</sup>			
IP00				
i6 g	≈ 0.36 g			

### **Cable outlets**

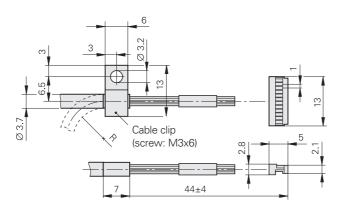
### **Electrical connection**

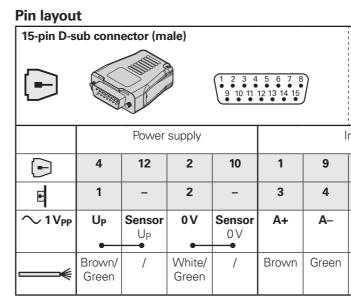


### **Connectors**



SHR-12V-S  $\sim$  1 V<sub>PP</sub>





**Shield** on housing;  $U_P$  = Power supply voltage

Sensor: The sense line is connected in the connector with the corresponding power line. Vacant pins or wires must not be used. <sup>1)</sup> Required for signal adjustment with the PWM 21

12-pin SHR-12V-S connector (female)							
E							
ncremental signals			Other signals				
3	11	14	7	13	8	6	15
6	5	8	7	9	12	10	11
B+	B-	R+	R–	Vacant <sup>1)</sup>	Н	/	Vacant <sup>1)</sup>
Gray	Pink	Red	Black	Violet	Green/ Black	Yellow/ Black	Yellow

#### Adapter cables and connecting cables

<b>PUR</b> 6 x (2 x 0.19 mm <sup>2</sup> ); $A_P = 2 \times 0.19 \text{ mm}^2$					
<b>PUR</b> 4 x (2 x 0.16 mm <sup>2</sup> ) + (4 x 0.5 mm <sup>2</sup> ); A <sub>P</sub> = 2 x 0.5 mm <sup>2</sup>		Ø8mm	Ø 6 mm <sup>1)</sup>		
<b>Adapter cable</b> with 15-pin D-sub connector (female) and 12-pin M23 connector (male)		331693-xx <sup>2)</sup>	355215-xx <sup>2)</sup>		
<b>Adapter cable</b> with 15-pin D-sub connector (female) and 15-pin D-sub connector (male)		354379-xx <sup>3)</sup>	355397-xx <sup>3)</sup>		
<b>Connecting cable</b> with 15-pin D-sub connector (female) and stripped cable end		354411-xx <sup>3)</sup>	355398-xx <sup>3)</sup>		
<b>Connecting cable</b> with 15-pin D-sub connector (female) and 15-pin D-sub connector (female) with pin layout for the IK 220		335077-xx <sup>2)</sup>	349687-xx <sup>2)</sup>		
<b>Signal cable</b> with stripped cable ends (15-polig) <sup>4)</sup>	→	816317-xx	816323-xx		

<sup>1)</sup> Cable length for  $\emptyset$  6 mm: max. 9 m

<sup>2)</sup> Without homing

<sup>3)</sup> With homing

<sup>4)</sup> Cable design:  $4 \times (2 \times 0.14 \text{ mm}^2) + (4 \times 0.5 \text{ mm}^2)$ 

 $A_P$ : Cross section of supply lines

#### Accessory

Adapter connector from SHR-12-V-S to D-sub for signal comparison with PWM 21

ID 1234385-01

## HEIDENHAIN

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This Product Information document supersedes all previous editions, which thereby become invalid. The basis for ordering from HEIDENHAIN is always the Product Information document edition valid when the order is placed.

#### (D) Further information:

Comply with the requirements described in the following documents to ensure correct and intended operation:

• Brochure: Modular Angle Encoders with Optical Scanning

- Brochure: Interfaces of HEIDENHAIN Encoders
- Brochure: Cables and Connectors

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